

IIT MADRAS Technology Transfer Office TTO - IPM Cell



Industrial Consultancy & Sponsored Research (IC&SR)

## Intelligent fire-fighting robot and method thereof **IITM Technology Available for Licensing**

## PROBLEM STATEMENT

Indian Institute of Technology Madras

- Generally, it is noted that existing fire-fighting systems that replace humans include mobile self-contained & remote-controlled robots which are capable of safely operating in a combustible atmosphere.
- Such robots in general include non-sparking & non-arcing electro-mechanical & electronic components including a positively pressurized enclosure that houses the electro-mechanical & electronic components to prevent intrusion of the combustible atmosphere into the enclosure.
- However, these clamping mechanisms are not flexible enough to adapt to different object dimensions for providing a precise grip over the objects and existing robots do not provide accurate and better gripping of the objects on the robot's path.
- Hence, there is a need to mitigate above challenges & provide efficient solution.

### INTELLECTUAL PROPERTY

### IITM IDF Ref. 2143; Patent No: 411358

**TECHNOLOGY CATEGORY/ MARKET** 

#### Technology: Fire fighter robot;

Industry: Industry; Applications: Industrial Application, Fire fighter robot;

Market: The global Fire fighter robot market is projected to grow at a CAGR of 9.7% during 2023 to 2031;

# TECHNOLOGY ALONG WITH IMAGE

- The present invention describes an intelligent and autonomous fire-fighting **robot** and method for moving in a hazardous field, detecting fires, and thereby extinguishing the fires.
- Said fire-fighting robot comprises a motion unit to move around in the hazardous field, a camera unit with multiple cameras to capture multiple frame images, and

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**IITM TTO Website**: https://ipm.icsr.in/ipm/

a fire sensing unit to detect the presence & depth of fires, &

a control unit with artificial intelligence that activates at least one robotic arm and fire extinguishing unit based on inputs received from the camera unit & the fire sensing unit. (Refer fig.1)

Said method is used for detecting and extinguishing fire & is capable of removing obstacles during the operation from the robot's path without human intervention, shown in Fig.2. The intelligent & autonomous fire-fighting robot is shown hereinbelow:



Reference Numbers:100-Fire Fighting Robot; 202/1,202/2-a pair of moving tracks connected to driving units(204/1, 204/2); 214-gripper end effectors; 208-cover, 206enclosure, 212-arm controlling motor, 216hose, 210-handle, 108-Robotic arm.

# TRL (TECHNOLOGY READINESS LEVEL)

TRL- 4, Proof of Concept ready& validated.

### **RESEARCH LAB**

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# TECHNOLOGY IMAGES



Figure 2: Illustrates a method for extinguishing the fire using the fire-fighting robot

# **KEY FEATURES / VALUE PROPOSITION**

\* Technical Perspective:

- 1. Provides an autonomous fire-fighting robot that is waterproof & temperature resistant & Said fire-fighting robot comprises oxygen mask.
- 2. Facilitates the autonomous fire-fighting robot that implements an inverse kinematics algorithm to determine joint angles and positions of gripper end effectors of a robotic arm comprised in the robot.

## \* Industrial Perspective:

- 1. Provides said robot that moves in any kind of terrain & uneven surface for monitoring & locating fires in a site, & operates effectively, quickly & safely.
- 2. Designed robot can effectively aid firefighters & thereby mitigate the effects of an accident. Hence, a quick & efficient response can be achieved at the right time which could save multiple lives.
- 3. Easily deploying the designed fire-fighting robot at desired locations either in single or multiple based on the requirement, where the location site must be monitored for fire accidents.

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