

# TTO - IPM Cell



## Industrial Consultancy & Sponsored Research (IC&SR)

### ANTI AIR COLUMN INTERACTION MOUNTING FOR MULTIROTOR AERIAL VEHICLES

### **IITM Technology Available for Licensing**

#### **Problem Statement**

- Increasing payload capacity by enlarging propellers results in undesirable size, weight, and stability issues.
- While VOOPS allows larger propellers without increasing footprint, it introduces thrust loss and system vibrations due to rotor overlap.
- Further, vibrations affect performance and stability, particularly in the accelerometerdependent control systems used for flight stabilization and navigation.

#### **Intellectual Property**

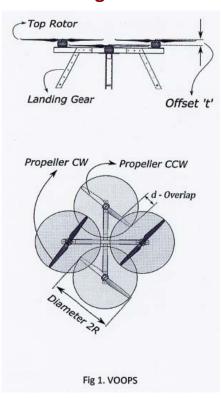
- IITM IDF Ref. 1383
- IN 509585 Patent Granted

#### **Technology**

Tilted Rotor Axes for Minimal Air Interaction: The quadcopter's frame design includes longitudinal members with motor mounts that tilt the rotor axes toward the central axis, reducing air interaction and improving column stability.

Wedge-shaped or Inclined Motor Mounts: The motor mounts, which can be wedge-shaped or inclined plane devices, are set at (5°-25°) predetermined angle achieve minimal air column overlap and maintain low vibration amplitude (0.1 g or less).

Configurable and Modular Design: The quadcopter can feature four, six, or eight longitudinal members, with overlapping rotors (0-35%) to optimize space and performance, and includes components like **ESC** communication units, and landing gear for comprehensive functionality.



#### **Technology Category/ Market**

Category - UAV (Unmanned Aerial Vehicle), **Aerospace & Defense Technologies** 

Applications - Aerial Photography, Agricultural Monitoring and Crop Management

**Industry - Aerospace and Defense, E-commerce** 

Market - Global multirotor drone market is projected to grow at a CAGR of 13.1% during the forecast period of 2024-2031.

#### TRL (Technology Readiness Level)

TRL - 5: Technology validated in relevant environment.

#### Research Lab

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#### **CONTACT US**

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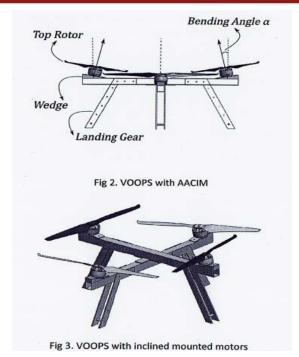


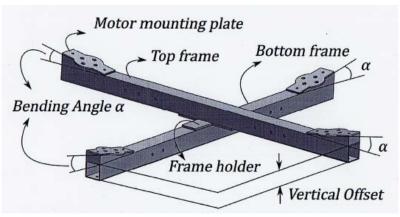
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VOOPS with AACIM Frame isometric view

#### **Key Features / Value Proposition**

Innovative design allows larger propellers without increasing the quadcopter's footprint, boosting payload capabilities.

1. Enhanced **Payload Capacity** 



- Tilted rotor axes minimize downwash interference. ensuring smoother and more stable flight performance.
- 2. Reduced Air Column Interaction



- Optimized rotor overlap and tilt angles achieve vibration amplitudes of 0.1 g or less, enhancing the reliability of
- 3. Low Vibration Levels:



- Configurable with four, six, or eight Iongitudinal members, offering flexibility and space efficiency for various applications.
- 4. Compact and Modular Design:



- Wedge-shaped or inclined motor mounts set at angles between 5°-25° improve rotor efficiency and flight stability
- 5. Advanced **Motor Mounts:**



- Equipped with ESC units and communication modules for precise speed control and robust data transmission.
- 6. Integrated Communication and Control **Systems**



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