IIT MADRAS Indian Institute of Technology Madras



Industrial Consultancy & Sponsored Research (IC&SR)

STEP CLIMBING APPARATUS IITM Technology Available for Licensing

Problem Statement

Conventional equipment cannot navigate the stepped and sloped terraces, leading to reduced farming productivity and manual labor.
Current climbing technologies are complex, bulky, expensive, and lack stability and adaptability for steep slopes.

• Autonomous agricultural robots are effective only on flat terrains and do not address the unique challenges of step farming.

Intellectual Property

- IITM IDF Ref. 2591
- IN 542650 Patent Granted

Technology

Advanced Climbing Mechanism: The step climbing apparatus features a gear train, telescopic slider unit, and a four-bar linkage system to enable efficient traversal of steps and steep slopes up to 90 degrees, enhancing mobility and stability on uneven terrains.

Active Control for Stability: The apparatus includes an active control mechanism and vibration-dampening features to prevent tilting and damage to the payload, ensuring stable operation while climbing and navigating irregular surfaces.

Versatile Applications: Designed for terraced agricultural fields, the apparatus can also be utilized in construction, industrial processes, and rescue operations, offering robust performance in challenging environments. FIG. 1. Schematic representation of a step climbing apparatus.



100	Step climbing apparatus
110	Housing
102	Gear train
108	Telescopic slider unit
104	Input gear
112	Four-bar linkage
116	Two front legs
106	Two rear legs
122	Linear actuator

TRL (Technology Readiness Level)

TRL - 4: Technology validated in lab scale.

Research Lab

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CONTACT US

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